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(57) Abstract:

Exemplary embodiments of the present disclosure directed towards a robotic assistant system to reduce manual efforts and perform multiple activities in real-time, comprising: at least one box configured to hold at least one robotic body, the at least one robotic body comprises a plurality of brushless motors with encoders for each motor, the robotic body is controlled by user voice commands; the at least one robotic body comprises at least two robotic arms configured to turn 3600 allow for articulated and interpolated movement to any point within the working envelope; and at least one width board configured to cover the box, a computing device, batteries, an electronic speed controller placed inside the box, the width board comprises a camera depth sensor, a hall sensor, and a lidar sensor, the computing device configured to process data and control a plurality of motors of the at least one robotic arm. FIG. 1

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